

**EE 559 Homework #2**  
**Due Monday September 19, 2016**

1. A 4-pole, 2.3 MW, 690 V, 50 Hz squirrel cage induction generator is used in a fixed-speed wind energy conversion system in Denmark (where the grid frequency is 50 Hz). Generator parameters are given below:

$$\begin{aligned} R_1 &= 0.001102 \, \Omega & X'_2 &= 0.0204 \, \Omega \\ X_1 &= 0.0204 \, \Omega & R'_2 &= 0.001497 \, \Omega \\ R_C &= \infty \, \Omega \\ X_m &= 0.6706 \, \Omega \end{aligned}$$

At a given wind speed, the machine operates at the rated speed of 1512 rpm. Neglecting windage and friction losses, determine the following:

- a. The slip, and the rotor speed in mechanical rad/sec and in electrical rad/sec;
- b. The stator and rotor currents;
- c. The developed power and torque;
- d. The stator and rotor winding losses;
- e. The generator efficiency and power factor.

Solution:

- a. The slip is given by:

$$s = \frac{n_s - n_r}{n_s} = \frac{1500 - 1512}{1500} = -0.008$$

The rotor speed in mechanical rad/sec is given by:

$$\Omega_m = n_m \frac{2\pi}{60} = 1512 \frac{2\pi}{60} = 158.336 \text{ rad/sec}$$

With 4 poles, the number of pole pairs is  $p=2$ . Therefore, the rotor speed in electrical rad/sec is given by

$$\omega_m = \Omega_m \times p = 158.336 \text{ rad/sec} \times 2 = 316.67 \text{ rad/sec}$$

- b. The 690 V is a line-to-line voltage. Therefore, we need to compute line-to-neutral voltage according to

$$V_1 = \frac{690}{\sqrt{3}} = 398.37 \text{ volts}$$

We will assume the applied voltage is the reference, therefore the applied voltage phasor is given by

$$\bar{V}_1 = 398.37 \angle 0^\circ \text{ volts}$$

The equivalent impedance is given by

$$Z_{gen} = R_1 + jX_1 + (R_C // jX_m) // (R'_2 + jX'_2 + R_{eq})$$

However,  $R_C$  is an open circuit, therefore

$$Z_{gen} = R_1 + jX_1 + (jX_m) // (R'_2 + jX'_2 + R_{eq})$$

We can compute  $R_{eq}$  as

$$R_{eq} = R'_2 \frac{1-s}{s} = 0.001497 \frac{1+0.008}{-0.008} = -0.188622$$

Therefore

$$Z_{gen} = 0.001102 + j0.0204 + \frac{(j0.6706)(0.001497 + j0.0204 - 0.188622)}{j0.6706 + 0.001497 + j0.0204 - 0.188622}$$

$$= 0.001102 + j0.0204 + \frac{(j0.6706)(-0.1871 + j0.0204)}{-0.1871 + j0.692497} = -0.1628 + j0.0844$$

$$= 0.1834 \angle 152.6^\circ$$

The stator current is then given by

$$\bar{I}_1 = \frac{\bar{V}_1}{Z_{gen}} = \frac{398.37 \angle 0^\circ}{0.1834 \angle 152.6^\circ} = 2172 \angle -152.6^\circ$$

The rotor current is then computed by current division:

$$\bar{I}'_2 = \bar{I}_1 \frac{jX_m}{jX_m + R'_2 + jX'_2 + R_{eq}}$$

$$= 2172 \angle -152.6^\circ \frac{j0.6706}{j0.6706 + 0.001497 + j0.0204 - 0.188622}$$

$$= (2172 \angle -152.6^\circ)(0.9042 - j0.2449)$$

$$= (2172 \angle -152.6^\circ)(0.9368) \angle -15.15^\circ = 2035 \angle -167.65^\circ$$

c. The developed power is given by:

$$P_D = 3 |\bar{I}'_2|^2 R_{eq} = 3(2035)^2 (-0.188622) = -2.343 \text{ MW}$$

The torque is given by

$$T_D = P_D / \Omega_m = (-2.343 \text{ E}6) / 158.336 = 14800 \text{ Nm}$$

d. The stator winding loss is given by:

$$P_{Loss,s} = 3 |\bar{I}_1|^2 R_1 = 3(2172)^2 (0.00102) = 15.60 \text{ kW}$$

The rotor winding loss is given by:

$$P_{Loss,r} = 3 |\bar{I}'_2|^2 R'_2 = 3(2035)^2 (0.001497) = 18.60 \text{ kW}$$

e. The generator efficiency can be computed as follows:

$$\eta = \frac{P_{out}}{P_{in}} = \frac{P_s}{|P_D|} = \frac{|P_D| - (P_{Loss,s} + P_{Loss,r})}{|P_D|} = \frac{2343 - (15.6 + 18.6)}{2343} = 0.9854\%$$

Observe that the induction generator is highly efficient!

The generator power factor depends on the power factor angle, which is the angle given by  $\theta = \theta_v - \theta_i$

i.e., it is the angle by which the applied stator voltage leads the stator current. Since from part (b), we have

$$\bar{V}_1 = 398.37 \angle 0^\circ \text{ volts}$$

$$\bar{I}_1 = 2172 \angle -152.6^\circ$$

then the power factor angle is given by

$$\theta = \theta_v - \theta_i = 0 - (-152.6) = 152.6^\circ$$

Then the power factor is given by

$$pf = \cos \theta = \cos 152.6^\circ = -0.888 \text{ (minus sign indicates "power in" is negative).}$$

This is a lagging power factor (consumes reactive power) because the current phasor is lagging the voltage phasor.